



ROBONEXUS

Saudi Arabia's Flagship Robotics Festival.

5 - 8 April 2026

RoboNexus Advanced Sumo Guidelines

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1. Introduction

1.1 Purpose

The ROBONEXUS Advanced Sumo Challenge is a robotics competition that tests mechanical design, programming intelligence, strategic thinking, and driver skill. Competitors aim to dominate the arena by outmaneuvering, outsmarting, and outperforming opponents in a series of physically and tactically demanding matches

1.2 Overview

Each match takes place in a specially designed circular arena where two robots compete to score points or push the other out of the ring ("Ring-Out"). Matches consist of three timed phases, combining autonomous operation and driver-controlled challenges.

The competition encourages innovation in:

- Robot engineering and control systems
- Sensor integration and precision movement
- Tactical decision-making and strategic gameplay

2. Match Format

Each match lasts up to 4 minutes, divided into three distinct phases:

Phase	Duration	Control Type	Objective
A: Classic Sumo	1:30	Autonomous	Push opponent out of the ring
B: Sumo + Skill Challenges	1:30	Switch/Manual	Continue Sumo battle while completing disk-placement challenges
C: Block Push Challenge	1:30	Switch/Manual	Win using the central block to push or eject the opponent

3. Arena Specifications

3.1 General Layout

- Shape: Circular
- Diameter: 4.00 meters
- Surface: Matte black finish to reduce glare and light interference
- Border: 5 cm wide white boundary line
- Edge: 10°–15° sloped perimeter

3.2 Marked Zones

- **Placement Zones:** Marked circles (20cm diameter) will be placed around the arena, where teams will receive extra points when placing the disks exactly on the marked zones.

(IMPORTANT NOTICE: Each team can only score if they place the disk in the opponent's placement zones)

- **Dead Zone:** Red-marked central area — staying inside this zone for more than 4 seconds consecutively results in a -5 point penalty

(IMPORTANT NOTICE: Pushing and blocking the opponent in the zone is permitted)

-The time spent in the zone will be precisely measured and counted aloud to ensure fairness and transparency during the match

- **Pit:** A square recess in the floor that causes immobilization if a robot falls in (no points awarded)
- **Block** (Phase C only): A central cube-shaped object used for indirect pushing



4. How to Win

A robot wins a match by either:
(Point scoring is explained in details in Section 5)

1. **Ring-Out Victory:** Opponent slides or exits the sloped edge (instant win at any phase)
2. **Reaching 12 Points:** Through cumulative scoring actions
3. **End-of-Match Points Lead:** If time expires, the robot with more points wins
4. **Instant 3-Disk Placement:** Placing all three disks successfully grants automatic match victory (As each disk is 4 points)

In the event of a **tie**, referees use the following tiebreakers:

1. Fewer fouls committed: the robot that broke rules less will win the round
2. Faster achievement of legal advantage

5. Scoring System

Goal: First to reach 12 points or cause a Ring-Out

Action / Event	Points	Phase	Notes
Successful Disk Placement	+4	B	3 disks = instant 12 pts = win
Legal Ejection using Block	+6	C	Must use the Block; no direct contact
Dead Zone Dwell $\geq 4s$ (cumulative)	-5	B/C	Penalty per occurrence
Illegal Direct Contact (Phase C)	-6	C	Major foul + reset
Pit Fall (Self)	0	B/C	Robot immobilized until extraction
Referee Style/Control Bonus	+1 (max +2/match)	All	Awarded for precise, safe, controlled edge-play
Ring-Out (Any Phase)	Instant Win	All	Opponent exits arena or slides onto slope

6. Robot Specifications

6.1 Dimensions & Weight

- Must fit within designated competition class limits (weight and footprint defined by event inspectors)
- Expansion after match start is allowed if it remains within safety and fairness limits

6.2 Power & Batteries

- All power systems must be safely fused.
- On-site charging stations must be approved

6.3 Actuation & Mechanisms

- Wedges, lifters, and linear actuators are allowed
- Prohibited: entangling mechanisms, sticky substances, liquids, flames, explosives, or projectiles.

6.4 Control & Autonomy

- Phase A: Fully autonomous operation (no driver input).
- Phases B & C: Manual control allowed via approved wireless controller or switch control.
- Emergency Stop (E-Stop): Required on all robots for instant disable.

7. Match Procedure

7.1 Pre-Match

- Robots undergo inspection and weigh-in
- Teams are given a short calibration window for sensor testing.

7.2 Start Sequence

- Robots are placed in their designated start zones.
- Referees confirm readiness.
- Countdown: "3...2...1...SUMO!" - Match begins.

7.3 Phase A: Classic Autonomous Sumo

- Flat arena, no obstacles.
- Objective: Push opponent out of the ring.
- Direct ring-out results in instant victory

7.4 Phase B: Controlled + Skill Missions

- Continue Sumo combat while completing disk-placement tasks in opponent's half.
- Each disk placed correctly = +4 points.
- Entering Dead Zone for ≥ 4 seconds = -5 penalty.
- If a robot falls into the Pit, it remains immobilized until reset.

7.5 Phase C: Block Push

- Direct robot-to-robot contact is forbidden.
- Use the Block to push or eject the opponent.
- Illegal bumper/body contact = -6 points and reset.
- Stalemates longer than 10 seconds may trigger a referee reset.

7.6 Pauses, Faults & Restarts

- Allowed for mechanical entanglement, safety issues, or arena fault.
- Restart from last safe position

7.7 End-of-Match

- Match ends at 12 points, ring-out, or time expiry.
- Scores confirmed by referees and displayed publicly

8. Fouls & Penalties

type	Description	Penalty
Warning	Minor unsafe or unsportsmanlike conduct	none
Minor Foul	Rule violation without impact on safety	-1 point
Major Foul	Safety breach, illegal contact, or repeated offense	-6 points
Disqualification	Severe or repeated misconduct	Match forfeited

9. Refereeing & Review

- Referees have full authority over match flow, scoring, and disputes.
- Video Review: Permitted for ring-outs, disk placements, or Dead Zone penalties (limited to 2 minutes).
- Score Sheets: Official forms must be signed by both teams and referees.
- Sportsmanship: All participants must maintain professionalism; misconduct may result in suspension or disqualification

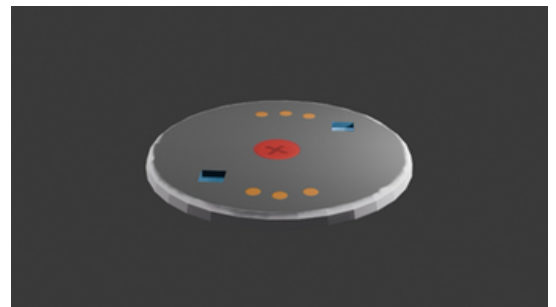
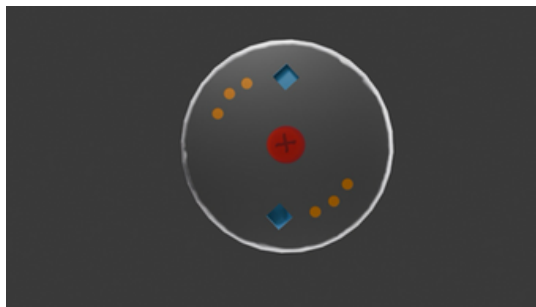
10. Safety & Inspections

- All robots must pass inspection before their first match.
- Post-inspection modifications require re-approval.
- Failing re-inspection = disqualification.
- Safety equipment, including E-Stop and shields, must be fully operational.

11. Appendices

A. Arena:

1. 3D design



2. Disk dimensions: Diameter: 20 cm Height: 7 cm



F. Referee Flowcharts: For fault and reset procedures

To ensure consistent and fair decision-making during matches, referees will follow predefined procedures in response to faults, disconnections, or unexpected behavior. The following flowchart logic applies:

• F-A. Fault & Reset Triggers

A referee may initiate a pause or reset under any of the following conditions:

- **Robot Disconnection:**

A robot loses wireless connection or becomes unresponsive to control.

→ Referee pauses match. Robot is allowed one reconnection attempt per match, and the match will be delayed (10 to 20 minutes).

- **Both Robots Are Immobile (Stalemate):**

Neither robot moves for more than 10 seconds, and no pushing or control is occurring.

→ Referee initiates a reset to previous positions, or moves to next phase (if near time limit).

- **Robot Falls into Pit:**

The robot is immobilized.

→ No reset; opponent continues match

- **Dead Zone Penalty:**

Robot remains inside the Dead Zone for ≥ 4 seconds consecutively.

→ Time is counted aloud; -5 points applied.

- **Illegal Contact (Phase C):**

Robot makes direct contact instead of using the block.

→ Immediate -6 point penalty and no reset.

- **Mechanical Entanglement:**

Robots are locked and cannot disengage.

→ Referee pauses match and repositions both to last safe positions.

- **Hardware Malfunction / Arena Fault:**

Any issue with the field, referee system, or robot hardware that affects fairness.

→ Referee pauses, documents the issue, and resets accordingly.



- **F-B. Reset Procedures**

1. Referee issues verbal "Pause!"

- a. Time is frozen; issue is identified and logged
- b. Robots are repositioned to the last known fair position
- c. Countdown resumes: "3...2...1...SUMO!"

Each team is allowed a maximum of 2 resets per match unless triggered by mutual entanglement or official fault.



G- Inspection Checklist: For technical review

INSPECTION CHECKLIST

Team Name:

Robot Name:

Inspector:

Date:

1. Size, Weight & Fit

Check Requirement

Pass (✓)Notes

- ☐ Robot fits within 50cm × 50cm footprint (without extending parts)
 - ☐ Robot weight ≤ 20Kg
 - ☐ Weight does not change post-inspection
 - ☐ No part of the robot extends outside the 50cm boundary before match start
-

2. Power & Safety

Check Requirement

Pass (✓)Notes

- ☐ Battery securely mounted and enclosed
 - ☐ No exposed wiring or short risk
 - ☐ Emergency Stop (E-Stop) present and functional
-

3. Mechanical Systems

Check Requirement

Pass (✓)Notes

- ☐ No entangling devices (e.g., ropes, nets)
 - ☐ No sticky substances or adhesives
 - ☐ No flames, sparks, explosives, liquids, or gases
 - ☐ Any wedges or lifters are smooth and safe
 - ☐ Wheels, treads, or mechanisms do not damage the arena
 - ☐ Any magnets or suction are non-damaging and pass impact test
-

4. Control & Autonomy

Check Requirement

Pass (✓)Notes

- ☐ Robot operates autonomously in Phase A
- ☐ Manual control systems function in Phases B & C
- ☐ Wireless controller complies with allowed frequencies
- ☐ Robot can switch control modes safely



5.Sensors & Navigation

Pass (✓)Notes

Check Requirement

- ☐ Robot can detect edge markings (5cm white line)
 - ☐ Obstacle and proximity sensors calibrated
-

6.Disk Handling (Phase B)

Pass (✓)Notes

Check Requirement

- ☐ Robot can carry 3 × 20cm disks
 - ☐ Gripper/mechanism does not damage disks
 - ☐ Placement mechanism allows precise release
-

7.General Safety & Arena Compatibility

Pass (✓)Notes

Check Requirement

- ☐ Robot does not scratch, dent, or mark the arena
 - ☐ All parts are secured (no loose parts/screws)
 - ☐ Safe for referees and audience
-

8.Final Check

Pass (✓)Notes

Check Requirement

- ☐ Robot passed full checklist with no critical issues
 - ☐ Team received a Pass / Conditional Pass / Fail result
-

Inspector Signature: _____

Team Captain Signature: _____

